An Efficient Lower Transition Rate Operator for the Sensitivity Analysis of Continuous-Time Markov Chains*

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Continuous-time Markov chains (CTMCs) are popular probabilistic models that describe the uncertain evolution of a dynamical system whose time domain is the non-negative reals $\mathbb{R}_{\geq 0}$. We assume that this system takes values in a non-empty and finite *state space* \mathscr{X} , with size $n := |\mathscr{X}|$. When a CTMC is *time-homogeneous*, it can be characterised—up to its initial distribution—by a single *rate matrix* Q. This is a $n \times n$ matrix with entries $Q(x, y) \in \mathbb{R}$, such that for all $x \in \mathscr{X}$, $\sum_{y \in \mathscr{X}} Q(x, y) = 0$ and $Q(x, y) \geq 0$ for all $y \in \mathscr{X}$ with $x \neq y$. We use \mathscr{R} to denote the set of all rate matrices.

When faced with uncertainty about the specification of a CTMC—be it with respect to the numerical parameters, or structural assertions like Markovianity or time-homogeneity—a sensitivity analysis may be performed using a continuous-time *imprecise*-Markov chain (CTIMC). This model can be seen as a *set* $\mathbb{P}_{\mathcal{Q}}$ of stochastic processes that are *consistent* with a non-empty bounded *set* $\mathcal{Q} \subset \mathcal{R}$ of rate matrices. One may consider different types of CTIMCs by including different types of models in $\mathbb{P}_{\mathcal{Q}}$. For example, one may include all time-homogeneous CTMCs characterised by the elements $Q \in \mathcal{Q}$. However, one could additionally include non-homogeneous CTMCs, or even more general—non-Markovian—processes; see Krak [1] for an analysis of these different types. Given a CTIMC $\mathbb{P}_{\mathcal{Q}}$, the associated (conditional) lower- and upper expectations $\mathbb{E}_{\mathcal{Q}}[\cdot|\cdot]$ and $\mathbb{E}_{\mathcal{Q}}[\cdot|\cdot]$ provide tight lower- and upper bounds, for any inference of interest, with respect to every model included in $\mathbb{P}_{\mathcal{Q}}$. To make this practicable, we need efficient methods to compute these lower- and upper expectations; by the well-known *conjugacy* property $\mathbb{E}_{\mathcal{Q}}[\cdot|\cdot] = -\mathbb{E}_{\mathcal{Q}}[-\cdot|\cdot]$, it suffices to focus on only the lower expectations.

Following Škulj [2], we associate with \mathscr{Q} its corresponding *lower transition rate operator* \underline{Q} , which is a map $\underline{Q}: f \mapsto \underline{Q}f$ from $\mathbb{R}^{\mathscr{X}}$ to $\mathbb{R}^{\mathscr{X}}$, where for all $f \in \mathbb{R}^{\mathscr{X}}$ and $x \in \mathscr{X}$, we let $\underline{Q}f(x) \coloneqq \inf_{Q \in \mathscr{Q}} Qf(x)$. Then for any $f \in \mathbb{R}^{\mathscr{X}}$ and $t \in \mathbb{R}_{\geq 0}$, the quantity $\underline{\mathbb{E}}_{\mathscr{Q}}[f(X_t)|X_0]$ can be conservatively bounded by the solution $\underline{f}_t \in \mathbb{R}^{\mathscr{X}}$ to the initial value problem

$$\frac{\mathrm{d}\underline{f}_{t}}{\mathrm{d}t} = \underline{Q}\underline{f}_{t} \quad \text{for all } t \in \mathbb{R}_{\geq 0}, \text{ with } \underline{f}_{0} = f.$$
(1)

That is, it holds that $\underline{f}_t(x) \leq \underline{\mathbb{E}}_{\mathscr{Q}}[f(X_t) | X_0 = x]$ for all $t \in \mathbb{R}_{\geq 0}$ and $x \in \mathscr{X}$; crucially however, this bound is satisfied with equality under some relatively mild assumptions on $\mathbb{P}_{\mathscr{Q}}$ and \mathscr{Q} [2, 1]. Hence in those cases, solving (1) amounts to computing the lower expectation of interest exactly. The differential equation (1) may be solved e.g. by iterative methods described by Škulj [2], Krak [1]. To apply these methods, we need an (ideally efficient) way to evaluate Qf for any $f \in \mathbb{R}^{\mathscr{X}}$.

We here consider a special **input:** Rate matrix $Q \in \mathscr{R}$, radius $r \in \mathbb{R}_{\geq 0}$, function $f \in \mathbb{R}^{\mathscr{X}}$ **output:** Function $\underline{Q}f \in \mathbb{R}^{\mathscr{X}}$, where \underline{Q} corresponds to $\mathscr{Q} = \mathscr{B}(Q, r) \subset \mathscr{R}$ case that we feel is important $(x_1,\ldots,x_n) \coloneqq \text{Sort}\overline{\text{Decreasing}}(\mathscr{X}, \overline{f}); // \text{ sort } \mathscr{X} \text{ such that } f(x_i) \ge f(x_{i+1}) \text{ for all } i \in \{1,\ldots,n-1\}$ for sensitivity analysis, where for $x \in \mathscr{X}$ do we construct a simple perturba $r_0 := r/2$ tion model for a given rate mafor $i \in \{1, ..., n\}$ do if $x_i = x$ then $\Delta_i \coloneqq r_{i-1}$ else $\Delta_i \coloneqq \min\{r_{i-1}, Q(x, x_i)\}$ trix Q; we let $\mathcal{Q} := \mathcal{B}(Q, r) :=$ $r_i \coloneqq r_{i-1} - \Delta_i$ $| \underbrace{\underline{Q}}_{f(x)} f(x) := \underbrace{Qf}_{i=1}^{r-1} \Delta_i \left(f(x_i) - f(x_n) \right)$ return \underline{Q}_f $\left\{ Q' \in \mathscr{R} : \|Q - Q'\|_{\infty} \leq r \right\}$ be the closed ball in \mathscr{R} of radius Algorithm 1: Efficiently evaluate Qf. $r \in \mathbb{R}_{>0}$ around Q. This \mathscr{Q} sat-

isfies the required properties to make the solution of (1) coincide with the lower expectation of interest [1, Prop. 6.20 and Cor. 6.25]. Our main current contribution is Algorithm 1, which enables the efficient computation of $\underline{Q}f$ in this case; for a proof of correctness, see Krak [1, Prop. 6.21]. It is easily seen that the runtime complexity of this algorithm is $O(n^2)$. This enables the exceptionally efficient computation of exact bounds on inferences under this perturbation model.

References

- [1] Thomas Krak. Continuous-Time Imprecise-Markov Chains: Theory and Algorithms. PhD thesis, 2021.
- [2] Damjan Škulj. Efficient computation of the bounds of continuous time imprecise Markov chains. Appl. Math. Comput., 250:165–180, 2015.

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